

Extension of Behaviours with Formal Data Types: Integration and Coordination

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Invited Lecture, Universities of Málaga and Extremadura

1 Introduction

2 Integration

3 Coordination

4 Conclusions

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2 Integration

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4 Conclusions

- 1 Introduction
- 2 Integration
- 3 Coordination
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The problem : complex systems

- expressive structuring needed
(modules \rightsquigarrow objects \rightsquigarrow components \rightsquigarrow aspects)
- encapsulated datatypes
- behaviours, communication, value-passing
- verification

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- formality

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Our framework

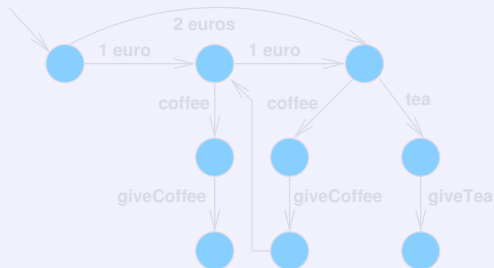
- formal components with BIDL
- expressive gluing mechanisms
- mixity: behaviours + abstract datatypes = STS
- analysis techniques for STS

LTS in everyday life

Labelled Transition Systems

Usual models for behaviours are LTS $\langle S, s_0, A, T \rangle$
 with $s_0 \in S$ and $T \subseteq S \times A \times S$, often, $A = A^{\text{in}} \uplus A^{\text{out}}$ (IOLTS)

Example (Coffee Machine)

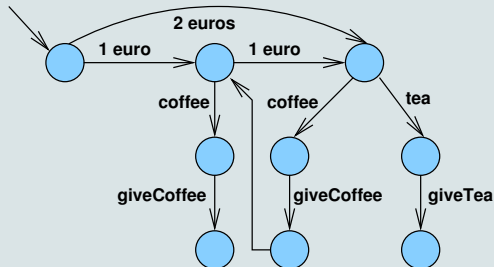


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State explosion

In presence of data ...

The computation of an LTS from a specification may explode !

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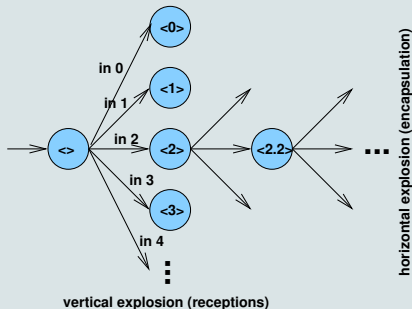
```
Buffer<>      = in  ?a:Nat .  Buffer<a>
Buffer<b.X>    = in  ?a:Nat .  Buffer<b.X.a>
               + out !b      .  Buffer<X>
```

State explosion

In presence of data ...

The computation of an LTS from a specification may explode !

Example (Buffer)



The STS Solution

Symbolic Transition Systems

STS abstract the data on states and transitions

[HL-HandbookPA,STS4LOTOS], [CPR00]

e.g., $\langle D, (\Sigma, Ax), S, s_0, v_0, T \rangle$ [MPR04]

with elements of T of the form:

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$$s \xrightarrow{[\text{guard}(\text{self}, x_1, \dots, x_n)] \text{ event? } x_1 \dots ? x_n ! t_1 \dots ! t_n / \text{action}(\text{self}, x_1, \dots, x_n)} s'$$

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Question

Are BIDL needed anyway ?

Yes

Question

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Yes

what does this component ?

FOOBAR

● result

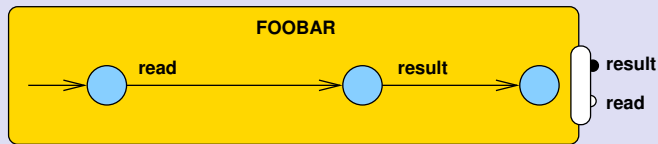
○ read

Question

Are BIDL needed anyway ?

Yes

it reads (something) and then outputs a result



Question

Are data needed anyway ?

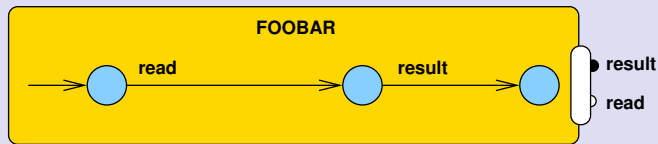
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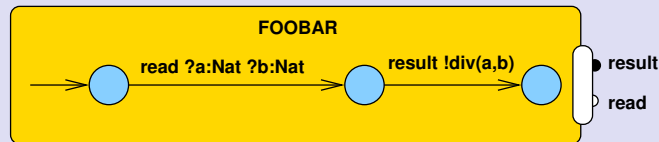


Question

Are data needed anyway ?

Yes

it reads (at a time) two integers and then outputs the result of the `div` operation applied to the integers

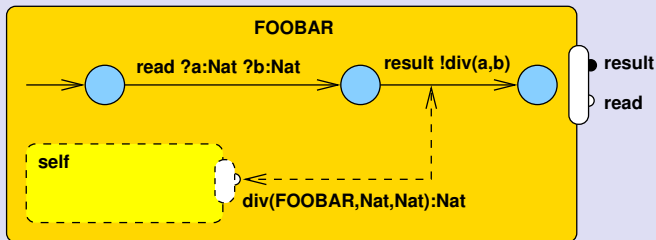


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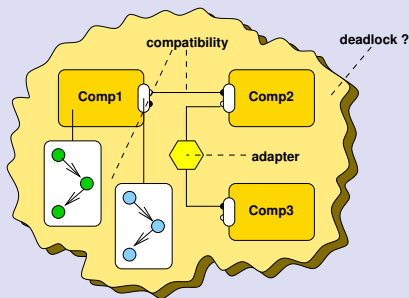
hidden underlying static type (with usual static signatures)



What does formality bring in ?

Some information in [PRS04]:

- abstract, expressive descriptions for BIDL
- animation
- equivalence checking, deadlock freedom, adaptors



Lots of mixed specification languages

kind	dynamic	static	examples
Heterogeneous	P. Alg.	model	ObjectZ-CSP, CSP-OZ, ZCCS, ZCSP, TCOZ
	P. Alg.	alg.	LOTOS, PSF
	T/S	model	$\mu\mathcal{S}\mathcal{Z}$, MaC, Event Calculus
	T/S	alg.	Korrigan , SDL, CASLChart, TAG
	T/S	– spec. –	Estelle, UML, Argos, BDL
	Petri Petri	alg. – spec. –	OBJSA, Clown, CO-OPN/2 CO, OPN
Homogeneous	Algebraic		LTL, Rewriting Logic, ASM
	Logical		TLA, Unity, TRIO, OSL
	Proc. Alg.		CCS+value, CSP, π -calcul

Formal + Semi-Formal

semi-formal

- + graph. notations, readability, expressiveness, structuring
 - UML (formal ?)
- tools, consistency ?
 - ArgoUML, SMW, UMLAut, ...

formal

- + abstraction
 - what not how
- + semantics
 - tools, verification
- not easy to learn and use

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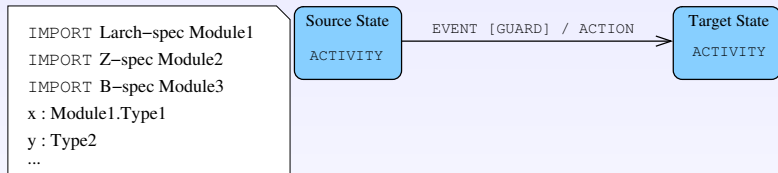
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Syntactic Extensions



transition part	interaction kind	example
EVENT	reception	$evt-name(x_1:T_1, \dots, x_n:T_n)$
GUARD	guard	<i>predicate</i>
ACTION	emission	$receiver \hat{=} evt-name(t_1, \dots, t_n)$
ACTION	assignment	$x:=t$

Typical Use: Case Study

The Gas Station

- furnishes different gas
- three pumps, three tanks
- credit card payment

Typical Use: Analysis

Static part

- booleans (Z)
- integers, real numbers (Larch)
- gases, pumps, tanks (Z)

Dynamic part

- card manager
- pump manager [3 Extended State Diagrams](#)
- tank manager

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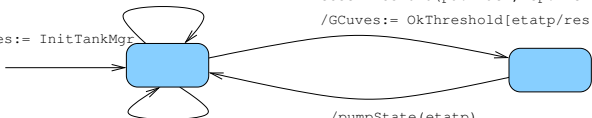
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Tank Manager

```
reduceQty(pp: NatZ, nqt: IntZ)
```

```
/GCuves:= UpdateQty[pp/pp?; nqt/qtte?]
```

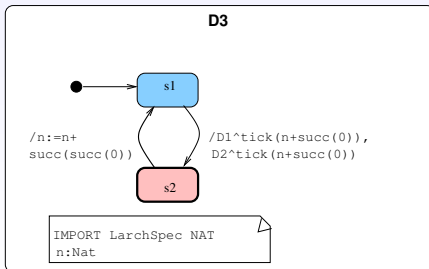
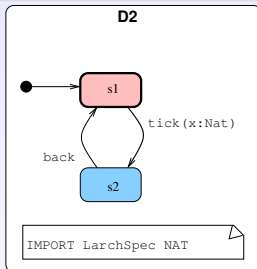
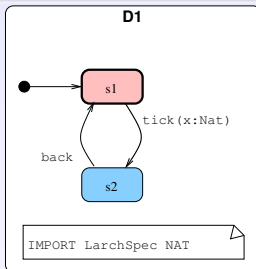
```
/GCuves:= InitTankMgr
```



```
augmentQty(pp: NatZ, nqt: IntZ)
```

```
/GCuves:= UpdateQty[pp/pp?; nqt/qtte?]
```

```
IMPORT Z-spec Z-donneeSE  
etatp: BoolZ
```



Operational Semantics – $\|\cdot\|_{\text{SOS}}$

On operational semantics ...

- can be used for Transition Systems and Process Algebras
- well suited for animation and equivalence checking
are the interfaces of C(client) and S(erver) compatible ?
- refinement
does the C implementation do what is required in its interface ?
- compositionality
if I prove that C and C' are compatible, may I replace C with C' in any system ?
- adequacy wrt temporal logic
if C and C' are equal, may I prove properties on the simplest one ?

Operational Semantics – $\|\cdot\|_{\text{SOS}}$

On operational semantics ...

- can be used for Transition Systems and Process Algebras
- *are the interfaces of C(lient) and S(erver) compatible ?*

$\text{Interf}(C) = \text{Interf}(S)$, with $= \in \{=_T, \sim, \approx, \dots\}$

- *does the C implementation do what is required in its interface ?*

$\text{Interf}(C) \subseteq \text{Interf}(\text{Impl}(C))$, with $\subseteq \in \{\subseteq_T, \subseteq_F, \dots\}$

- *if I prove that C and C' are compatible, may I replace C with C' in any system ?*

$C \sim C' \Rightarrow (\forall S[.]. S[C] \sim S[C'])$

- *if C and C' are equal, may I prove properties on the simplest one ?*

$C \sim C' \Leftrightarrow (\forall \phi \in \Phi_{\text{HML}}. C \models \phi \Leftrightarrow C' \models \phi)$

The [APS03] Semantics

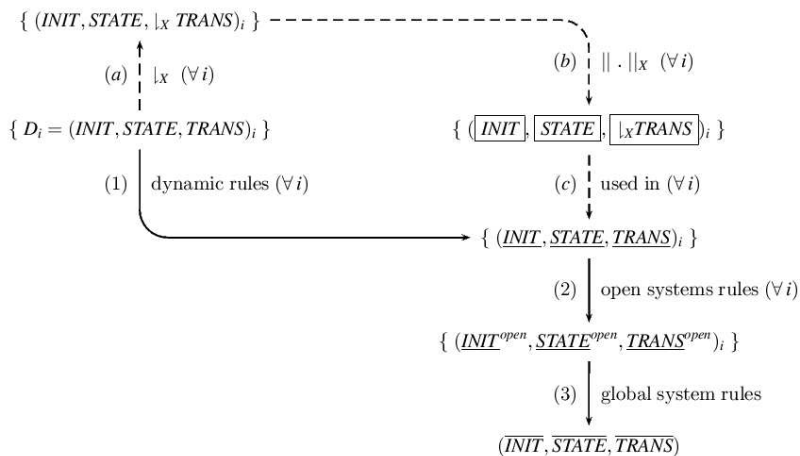
- based on experience with several mixed languages (Korrigan, CCS+ADT, TAG, MaC, ...)
- representative for the definition of a generic approach to integrate static formal specifications (SFS) into dynamic formal specification (DFS)
 - builds on a first proposal for UML state diagrams + SFS + synchronous communication
 - generalizing and asynchronous communication

Principle

Formal rules in 4 layers

- meta-typing
- static evolution
- dynamic evolution and open-systems
- composition

Principle



Remarks

- lots of dynamic semantics
 - use of generic elements, e.g., *event* $\boxed{\in} Q_{in}$

Constraints

- $\|D\|_{\text{SOS}} = \text{LTS}(\boxed{INIT}, \boxed{STATE}, \boxed{TRANS}) \Rightarrow \text{OK}!$

Notation

- $\mathcal{D}, D = (INIT, STATE, TRANS, DeclImp, DeclVar) \in \mathcal{D}$
- $EVENT = EVENT^? \cup EVENT^!, DeclVar = DeclVar^? \cup DeclVar^!$
- $S \subseteq \boxed{STATE} \times \mathcal{E} \times \boxed{Q}[EVENT^?] \times \boxed{Q}[EVENT^!]$

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Static Evolution

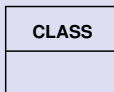
$$\frac{\forall i \in 1..n . \exists X_i . t_i ::_D X_i \quad \exists v_i . E \vdash t_i \triangleright_{X_i} v_i}{act\text{-eval}(\text{rec} \hat{e}(t_1, \dots, t_n), \langle \Gamma, E, Q_{in}, Q_{out} \rangle, D) = \langle \Gamma, E, Q_{in}, Q_{out} \boxplus \{\text{rec} \hat{e}(v_1, \dots, v_n)\} \rangle}$$

$$\frac{\exists X . t ::_D X \quad \exists v . E \vdash t \triangleright_X v}{act\text{-eval}(x := t, \langle \Gamma, E, Q_{in}, Q_{out} \rangle, D) = \langle \Gamma, E\{x \mapsto v\}, Q_{in}, Q_{out} \rangle}$$

Static Evolution

Term evaluation, \triangleright_X

- \triangleright_{Alg} : rewriting (+ tools : Larch Prover, ELAN)
- $\triangleright_Z, \triangleright_B$: LTS construction (+ tools : Z-Eves)
- \triangleright : classes formelles, Z



Dynamic Evolution

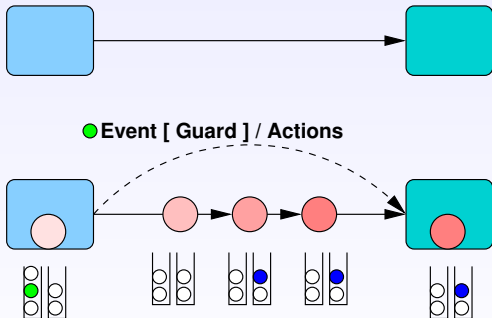
Notation

$$EVENT^{?+} = EVENT^? \cup \{\varepsilon\}$$

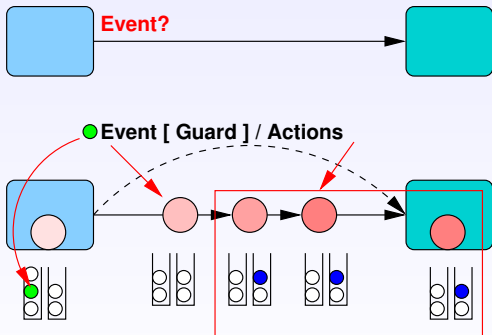
$\|D\|_{\text{sos}} = LTS(\underline{INIT}, \underline{STATE}, \underline{TRANS})$ with:

- $\underline{STATE} \subseteq S$
- $\underline{INIT} \subseteq \underline{STATE}$
- $\underline{TRANS} \subseteq \underline{STATE} \times EVENT^{?+} \times \underline{STATE}$

Dynamic Evolution



Dynamic Evolution



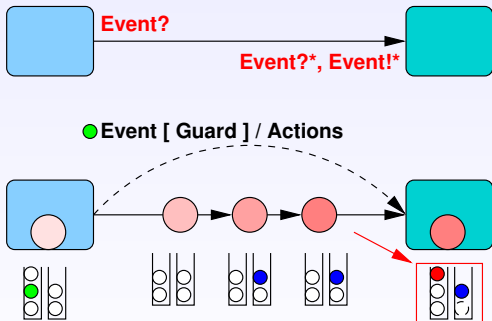
Open Systems

Notation

$\|D\|_{SOS}^{open} = LTS(\underline{INIT}^{open}, \underline{STATE}^{open}, \underline{TRANS}^{open})$ with:

- $\underline{INIT}^{open} \subseteq \underline{INIT}$
- $\underline{TRANS}^{open} \subseteq \underline{TRANS} \times \boxed{Q}[EVENT?] \times \boxed{Q}[EVENT!]$
- $\underline{STATE}^{open} \subseteq \text{SOURCE}(\underline{TRANS}^{open}) \cup \text{TARGET}(\underline{TRANS}^{open})$

Open Systems



Compositions

Notation

$\|\cup_{i \in 1..n} D_i\|_{oper}^{open} =$
 $LTS(\overline{INIT}^{open}(\cup_{i \in 1..n} D_i), \overline{STATE}^{open}(\cup_{i \in 1..n} D_i), \overline{TRANS}^{open}(\cup_{i \in 1..n} D_i))$
 with:

- $\overline{INIT}(\cup_{i \in 1..n} D_i) \subseteq \prod_i \overline{INIT}^{open}(D_i)$
- $\overline{TRANS}(\cup_{i \in 1..n} D_i) \subseteq \{t \in \prod_i \overline{TRANS}^{open}(D_i) \mid CC(t)\}$
- $\overline{STATE}(\cup_{i \in 1..n} D_i) \subseteq$
 $\overline{INIT}(\cup_{i \in 1..n} D_i) \cup \overline{TARGET}(\overline{TRANS}(\cup_{i \in 1..n} D_i))$

Compositions

Idea

whenever

*something addressed to D_j
is taken out of a given D_k output queue*

then

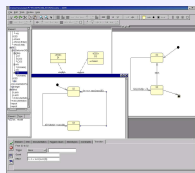
*it is put, **at the same time**, within the D_j input queue*

Compositions

Formally ...

$$\begin{aligned}
 & CC(S_1 \xrightarrow{I_1}_{E_{in_1}, E_{out_1}} S'_1, \dots, S_n \xrightarrow{I_n}_{E_{in_n}, E_{out_n}} S'_n) \Leftrightarrow \\
 & \forall k \in 1 \dots n. \forall D_j \hat{=} e \in E_{out_k} . D_j \in \cup_{i \in 1 \dots n} D_i \implies e \in E_{in_j}
 \end{aligned}$$

xCLAP - Architecture



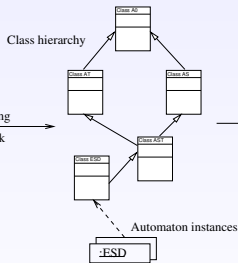
SMW

Translator
 smw2xclap

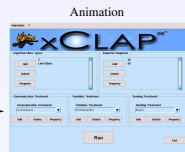


State diagrams
 (textual format)

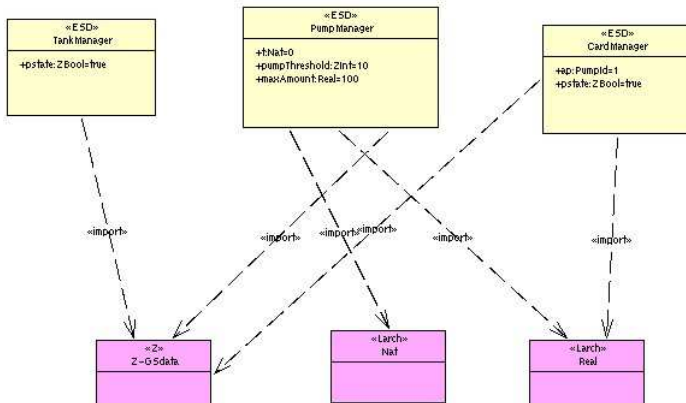
Parsing
 Spark



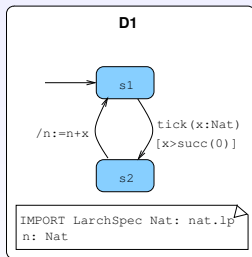
Data tools



xCLAP - Designing

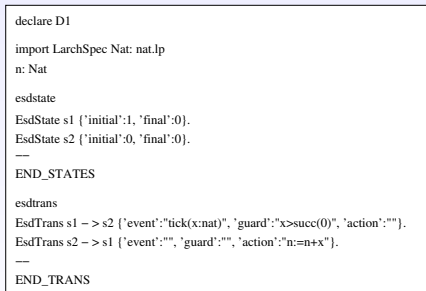


xCLAP - Translation



(a) state diagram (graphical format)


Translator
 →
smw2xclap



(b) state diagram (textual format)

xCLAP - Configuration

Animation ?



xCLAPTM

Imported Meta-types

Add Z LarchSpec

Delete

Property

Imported Diagrams

Add d2 d3

Delete

Property

Communication Treatment

Communication Treatment
synchronous

Add Delete Property

Variables Treatment

Variables Treatment
FirstSemantics

Add Delete Property

Sending Treatment

Sending Treatment
binary

Add Delete Property

xCLAP - Animation

The screenshot shows the xCLAP tool interface. The main window is titled "Diagram: D1" and contains the following text:

System State

Global Variable
 ('x', 'Nat', 'LarchSpec', 's(s(s(0)))')
 Current State: e2

Choice

e2 -> e1 {'event':, 'guard':, 'action':x:-s(x)}.
 e2 -> e3 {'event':, 'guard':((s(s(0))) < x), 'action':{D2,D3}.tick(x)}.

System after Simulation

Global Variable
 ('x', 'Nat', 'LarchSpec', 's(s(s(0)))')
 Current State: e3
 Transitions
 e3 -> e3 {'event':tack(x), 'guard':, 'action':}.

On the right side, there is a tree view showing the state of three diagrams:

- D1**
 - Global Variables
 - x : Nat : LarchSpec : s(s(s(0)))
 - Current State: e2
- D3**
 - Global Variables
 - y : Nat : LarchSpec : 0
 - Current State: g1
- D2**
 - Global Variables
 - t : Nat : LarchSpec : 0
 - Current State: f1

At the bottom right, there are navigation icons for back, forward, and search.

What do we model ?

Distributed Entities

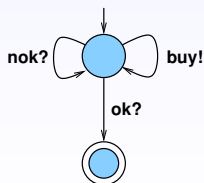
- viewed through **interfaces** (black-box foundation)
- interfaces have to take into account **behavioural information** (BIDL)
- goal: quick survey and comparison of **formal material** to describe coordination/interaction among entities
- remember ?
formal means enable one to use existing **verification tools** to ensure correctness of interactions
- applications: web services, genetic regulatory networks

How ?

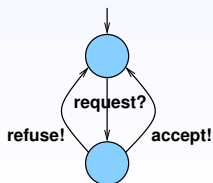
A Simple Formal Model: LTS

- here: simple yet general **formal model** of entities:
a nondeterministic **LTS** $\langle L, S, I, F, T \rangle$
- labels may be emissions $e!$ or receptions $r?$
- **data information** is discarded for simplicity
- running example: one store and several suppliers

Store



Supplier

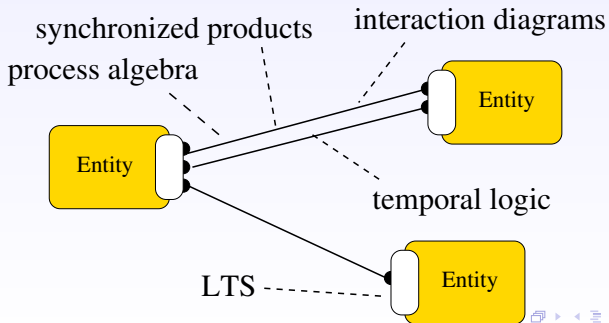


[YellinEtAl-TOPLAS'97]
[deAlfaroHenzinger-ESEC'01]

[ArbabEtAl-FOCLASA'02]

Communication Model

- depends on the means used to compose entities
- **implicit means**: semantic rules (first part)
- **explicit means**



Semantics

- basic idea: redefine the *CC* constraint of part I

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$$CC(S_1 \xrightarrow{I_1}_{E_{in_1}, E_{out_1}} S'_1, \dots, S_n \xrightarrow{I_n}_{E_{in_n}, E_{out_n}} S'_n) \Leftrightarrow$$

$$\forall k \in 1 \dots n . \forall D_j \hat{e} e \in E_{out_k} . D_j \in \cup_{i \in 1 \dots n} D_i \implies e \in E_{in_j}$$

Semantics

- basic idea: redefine the CC constraint of part I

$$CC(S_1 \xrightarrow{I_1} E_{in_1}, E_{out_1} S'_1, \dots, S_n \xrightarrow{I_n} E_{in_n}, E_{out_n} S'_n, \text{Coord}) \Leftrightarrow$$

???

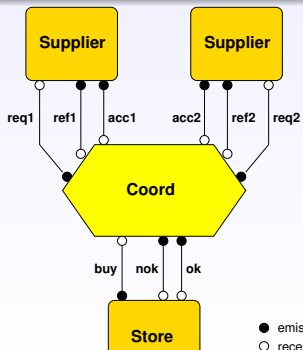
- see [SP04], [JUCS, 2005, submitted]
- here: examples

Process Algebra

- **parallel composition operators** are way to match inputs and outputs
- may be used as an **explicit 1st class coordinator language** to take into account more complex coordination protocols

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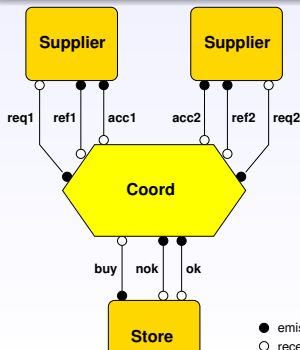
Example (with processes)

```
S = Supplier[req1/request, ref1/refuse, ..]
  | Supplier[req2/request, ref2/refuse, ..]
  | Store
  | Coord
Coord = buy.( 'req1.Wait1 + 'req2.Wait2)
Wait1 = acc1.'ok .0 + ref1.'nok.Coord
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```

[SalaünEtAl-IJBPIIM]

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Synchronized Products

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synchronous, one to many: $\langle a!,\varepsilon,b?,\varepsilon,c? \rangle$

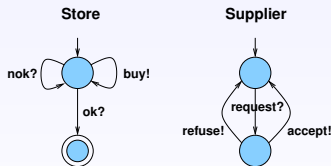
synchronous, matching: $\langle a!,\varepsilon,b!,\varepsilon,c! \rangle$

synchronous, generation: $\langle a?,\varepsilon,b?,\varepsilon,c? \rangle$

asynchronous, one to many: $[a!,\varepsilon,b?,\varepsilon,c?]$

Synchronized Products

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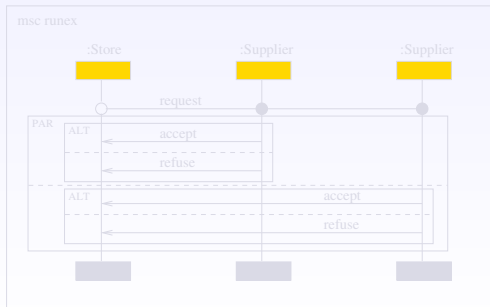
Example (with vectors)

$\langle \text{buy!}, \text{request?}, \text{request?} \rangle$
 $\langle \text{nok?}, \varepsilon, \text{refuse!} \rangle$
 $\langle \text{nok?}, \text{refuse!}, \varepsilon \rangle$
 $\langle \text{ok?}, \varepsilon, \text{accept!} \rangle$
 $\langle \text{ok?}, \text{accept!}, \varepsilon \rangle$

Interaction Diagrams

- coordination may be described using interaction diagrams: **MSC**, or UML **sequence** and **collaboration diagrams**
- many formalisations proposed so far

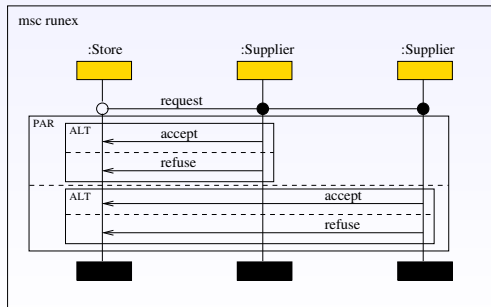
[ITU-MSC'96, MauwReniers-MSC'96, KrügerEtAl-SFEDL'02]



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Temporal Logic

- numerous: LTL, CTL/CTL*, ACTL, TLA, μ -calculus,...
- expressive means to coordinate entities, e.g. in formal ADLs [JUCS, 2005, submitted]
 - first, being able to describe the **properties of objects** that are to be glued (states and transitions)
 - **indexed formulas**, then lift the properties of the subcomponents of a composition up to the composition
 - the logic also takes into account coordination using **logical conjunction**

Example (with logic)

```
Store.buy!  $\Leftrightarrow$  ALL( $\{i : [1..N]\text{Supplier}_i\}$ ).request?  
✓ Store.ok?  $\Leftrightarrow$  ONE( $\{i : [1..N]\text{Supplier}_i\}$ ).accept!  
✓ Store.nok?  $\Leftrightarrow$  ONE( $\{i : [1..N]\text{Supplier}_i\}$ ).refuse!
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A First Comparison

		Process Algebras	Vectors	Interaction Diagrams	Logics
Communication Expressiveness	1 to 1	yes +	yes ++	yes ++	yes ++
	1 to N	yes	yes	yes	yes
	1 to M in N	extension	yes	yes	yes
Communication Expressiveness	Name matching	no +	yes +	no -	yes +
	Data	yes	extension	no	yes
	Order	yes	no	yes	no
User Friendliness	Tools	animation equivalence checking model-checking ++	animation equivalence checking model-checking +	animation model-checking +	embeddings -
	Executability	yes	no	yes	no
	Graphical notations	no -	no -	yes ++	no --

Conclusions

Overview

- semantics for STS: operational (here), denotational
- partially tool-equipped: animating (xCLAP), PVS embedding
- semantics for different coordination means

Perspectives

- framework for STS (Eclipse)
- implement coordination means
- better verification means
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Any questions ?

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